

Discrete iterations for computing generalized inverses of time-varying matrix

Marko D. Petković¹, Predrag S. Stanimirović¹, and Vasilios N. Katsikis²

¹Department of Computer Science, Faculty of Sciences and Mathematics, University of Niš, Serbia, dexterofnis@gmail.com, pecko@pmf.ni.ac.rs

²Department of Economics, Division of Mathematics and Informatics, National and Kapodistrian University of Athens, 10559 Athens, Greece, vaskatsikis@econ.uoa.gr

We consider discrete-time iterative methods for computing inverse and pseudoinverse of time-varying matrices. These methods are obtained by discretizing corresponding ZNN (Zhang Neural Network) models. The proposed schemes incorporate scaled Hyperpower iterative methods as well as the Newton iteration in certain cases. We apply the general linear Multi-step method to obtain the general discretization rule. It comprises all previously proposed discretization schemes, including Euler and the Taylor-type difference rules. One particular rule, based on the 4th order Adams-Bashforth method, is proposed and numerically compared with other known iterative schemes. In addition, we propose the extension of the ZNN model for pseudoinverse computation of singular or rectangular matrices. Convergence properties of the continuous-time ZNN model in the case of the Moore-Penrose inverse and its discretization are also considered.

References

- [1] D. Guo and Y. Zhang, Zhang neural network, Getz-Marsden dynamic system, and discrete-time algorithms for time-varying matrix inversion with application to robots' kinematic control, *Neurocomputing* **97** (2012), 22–32.
- [2] M. D. Petković, Generalized Schultz iterative methods for the computation of outer inverses, *Comput. Math. Appl.* **67**(10) (2014), 1837–1847.
- [3] M. D. Petković and P. S. Stanimirović, Two improvements of the iterative method for computing Moore-Penrose inverse based on Penrose equations, *J. Comput. Appl. Math.* **267** (2014), 61–71.

- [4] L. Jin and Y. Zhang, Discrete-time Zhang neural network of $\mathcal{O}(\tau^3)$ pattern for time-varying matrix pseudoinversion with application to manipulator motion generation, *Neurocomputing* **142** (2014), 165–173.
- [5] Y. Zhang, D. Guo, Y. Yin and Y. Chou, Taylor-type 1-step-ahead numerical differentiation rule for first-order derivative approximation and ZNN discretization, *J. Comput. Appl. Math.* **273** (2015), 29–40.
- [6] Y. Zhang, Y. Wang, L. Jin, B. Mu and H. Zheng, Different ZFs leading to various ZNN models illustrated via online solution of time-varying underdetermined systems of linear equations with robotic application, *Lecture Notes in Comput. Sci.* **7952** (2013), 481–488.