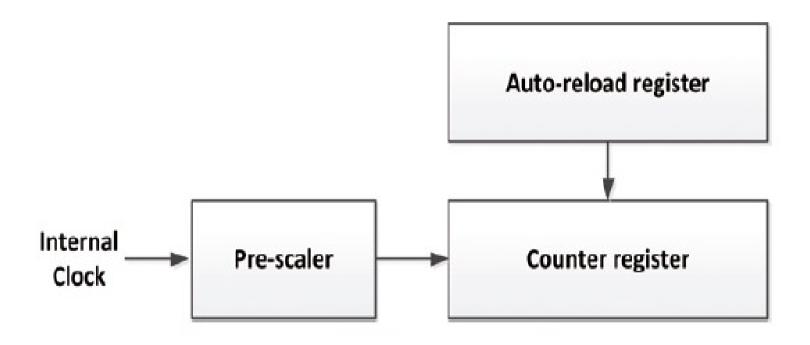
Tajmerski prekid



Tajmerski prekid

The following equation can be used to determine the values to be loaded to generate interrupts at specified times:

$$I = \frac{(P+1)(A+1)}{f}$$

or,

$$A = \frac{f \times I}{(P+1)} - 1$$

where

A is the value to be loaded into the auto-reload register;

I is the required interrupt time in seconds;

f is the clock period in Hz;

P is the prescaler value (1 to 65535).

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P is the prescaler value (1 to 65535).

For example, with 80 MHz clock, for 1-second timer interrupts, assuming P=39999, we have:

$$A = \frac{80,000,000 \times 1}{(39999+1)} - 1 = 1999$$

Description

In this project the on-board LED (at port PA5) is flashed every second using timer interrupts.

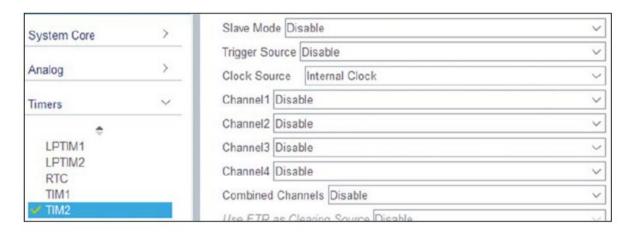
The aim

The aim of this project is to show how timer interrupts can be used in a program.

- Configure PA5 as digital output.
- Configure the MCU clock as 80 MHz and make sure that the APB1 clock is set to 80 MHz.
- Click Timers, then click TIM2, and select the Clock Source as Internal clock

Obratiti paznju na max clock za konkretan MCU!!!

 Click Timers, then click TIM2, and select the Clock Source as Internal clock (Figure 6.3).



- Under Configuration, click on Prescaler (PSC 16-bit value) and make sure it is set to Decimal and change its value to 39999.
- Change the Counter Mode to Down.
- Click on Counter Period (Auto reload register) and make sure it is set to Decimal. Change its value to 1999.
- Click Internal Clock Division and set it to 2. Notice that this is not clock division, but it relates to the filter at the input sampler.
- Click auto-reload preload and click to Enable it.
- Click System Core followed by NVIC. Click to enable TIM2 global interrupt.
- Click File, followed by Save and click YES to generate code.

You should now open the generated code. Notice that the following code is included for the timer interrupt (comments are removed for clarity):

The following timer related code is included in the program:

```
TIM_HandleTypeDef htim2;
```

You should add the following code just before the **while** loop in the main program to enable timer interrupts:

```
HAL_TIM_Base_Start_IT(&htim2); // Enable the timer
```

Also, the timer interrupt service routine should be added before the main program as shown below. Notice that the LED control code to toggle the LED is inside the timer interrupt service routine.

```
void HAL_TIM_PeriodElapsedCallback(TIM_HandleTypeDef *htim)
{
          HAL_GPIO_TogglePin(GPIOA, LED);
}
```

```
int main(void)
{
   HAL_Init();

   SystemClock_Config();

   MX_GPIO_Init();
   MX_TIM2_Init();
   HAL_TIM_Base_Start_IT(&htim2);

   while (1)
   {
   }
}
```